REMUS HARRIS

Roslindale, MA, 02131 | TEL: 617-420-6556 | remus@bu.edu | remusharris.com

EXPERIENCE

Boston University Rocket Propulsion Group | Boston University

- Led development of a web-based graphical user interface for controlling our hardware over network, which has become the standard client-side software used to control/monitor all our DAQ and control systems
- Designed a long-range video and telemetry system for a liquid bipropellant rocket with an expected apogee of 30,000 ft, allowing the team to view vital rocket statistics during and after flight
- Developed a flight computer for data collection and parachute deployment of a supersonic 600 lbf solid-motor rocket, enabling the team's first successful flight and recovery in 6 years
- Designed the team's power distribution box, providing a universal interface and central hub for powering and controlling all the team's electronics, ground support hardware, and cameras/telemetry systems
- Created a battery management system, which facilitates a seamless transfer between ground power and a flight battery, while protecting against brownouts, surges, reverse current, and potential disconnections

Firmware Engineering Summer Internship | Rockwell Automation

- Optimized a legacy SQL database, improving query times by more than 50x, bringing the average query time from 5-10 seconds to 5-20 milliseconds
- Added networking functionality to a DWARF file viewer tool, allowing for real-time streaming and monitoring of internal hardware values
- Implemented graphing and logging features for motor data, allowing for better visualization and data analysis
- Removed the need for a complex dependency tree, allowing the application to be run with only standard windows dependencies
- Migrated legacy projects from Qt4 to Qt5, leveraging new features for enhanced user interface and software functionality
- Authored multiple detailed technical guides detailing porting strategies for Qt projects, facilitating smooth project transitions for future developers

PROJECTS

Design and Construction of a Human-Carrying Drone | Independent Project

- Designed and constructed a modular heavy-lift human-carrying drone, capable of 30 minutes of unmanned flight and 12-15 minutes of manned flight
- Achieved ~68.5 lbs of thrust per arm with a coaxial configuration of 16 high-torque 8318 MAD motors, each connected to 34x10.5" folding propellers, leading to a combined thrust of ~548 lbs
- Engineered a custom power system with 16 LiPo batteries arranged into four 2S2P blocks, providing 44.4V to each pair of arms for balanced power distribution
- Adapted an agricultural drone flight computer, creatively solving limited PWM output by wiring electronic speed controllers in parallel for synchronized control
- Constructed the frame using aluminum square tubing, repurposed materials, and a modular design that allowed for reconfiguration of 4 or 8 arms for varied flight modes
- Independently acquired all technical knowledge and skills necessary for project completion, enhancing self-sufficiency and resourcefulness in engineering

EDUCATION

SKILLS

Boston University | Boston, MA B.A. in Computer Science - **GPA: 3.67**

Relevant Coursework:

Computer Systems with a focus on Linux, Assembly, and C Computer Science Fundamentals 1 and 2 using Python and Java

Languages: C++, C, Python, Java, JavaScript/TypeScript, HTML, CSS, Shell, SQL, Assembly (limited knowledge) Platforms and Tools: Windows, Linux, MySQL, MongoDB, NextJS, Django, Flask, Docker, VMware, Qt, Git Other: Embedded Systems, Real-Time Control, PCB Design, Server Management and Administration, Networking Services, Web App Development, Agile Design Methodology, Willingness and ability to learn new skills as needed

Expected Graduation May 2025

Database Systems and Optimization using SQL and MongoDB

Full Stack Web App Development

May 2024 - August 2024

August 2021 - Current

.

June 2020 - June 2021